

SSA Capabilities and Policies Academia/Scientific

Brandon A. Jones, Ph.D. Assistant Professor Thursday January 24, 2019



Example Roles in SSA

- **Operators** Maintain and advance the state of practice
- **Industry** Transition state of the art into practice
- Academia Advance the state of the art
 - Academics must *actively promote* advancements to operators and industry to remain relevant!
 - Academia is better suited to the exchange of new ideas and impartial comparison between algorithms and methods



Advance understanding and state of the art



Image: Tuggle and Zanetti, 2018



- SSA estimation problems are fundamentally nonlinear.
- Academia has led the advancement of Bayesian inference for nonlinear systems
- Description on figure from previous slide:
 - Left Figure A prior distribution for a 2-D estimated state vector
 - Middle Figure A single measurement of distance from the origin (Gaussian noise/error)
 - Right Figure Posterior distribution given prior and measurement
- In this scenario, classical methods such as the Kalman filter, extended Kalman filter, and the unscented Kalman filter fail.



Consider high-risk, high-reward ideas for SSA





- Accuracy of propagators in SSA classically limited by computation resources
- Computational expense of gravity model limits accuracy for propagation of low-Earth objects.
- Jacobian also relies on gravity model
- Research in leveraging modern computers makes gravity model runtimes constant with an increase in memory requirements
- Gravity model runtimes can be greatly reduced.



• Question assumptions that are considered fact

TLEs classically considered incompatible with special perturbation methods.

Advancements in "hard" and "soft" information fusion demonstrate otherwise





- Combining Two-Line Elements (TLEs) and special perturbations methods of orbit determination/propagation have traditionally been infeasible
- Combining methods of "hard measurements" (quantifiable measurements with known uncertainty) with "soft measurements" (not quantifiable or measurements with unknown uncertainty) enable improved estimation performance
- New methods of hard/soft information fusion allow for maximizing information gained from data
- Image description:
 - Blue vertical bars are times where a new TLE is available
 - Vertical orange bars are time with a new range measurement
 - Including the TLE as soft information improves accuracy until a sufficient number of hard measurements are available.



• Train the future researchers and operators in SSA









SSA – A Multi-disciplinary Problem

- Applied Mathematics
- Astronautics
- Astronomy
- Computer Science
- Engineering Mechanics
- Information Fusion

- Material Science
- Psychology
- Policy
- Remote Sensing
- Space Weather
- Others...



Space Object Interaction with Environment





Space Environment

To maintain SSA, must understand the spacecraft's interaction with its environment ۲

You must measure it to know it; you must predict it to understand it. - Moriba Jah, UT-Austin

- Conservative forces •
 - Gravity (Earth and other bodies)
 - Aspherical gravity and its temporal variations _
 - Relativistic forces _
- Non-Conservative forces
 - Solar radiation pressure _
 - Earth radiation pressure _
 - Thermal radiation _
 - Maneuvers
 - Electrostatic charging _
 - Outgassing



Knowledge of Orbit State

• Orbit state and uncertainty propagation





Knowledge of Orbit State

- Knowledge of orbit state is a function of many elements
 - Knowledge of the spacecraft
 - Knowledge of the environment
 - System requirements
 - Computational resources
- How do we translate knowledge of a spacecraft into predicted knowledge of the state?
 - Sensitive to what is known about the spacecraft
 - How do we accurately account for systematic and random errors?
 - How do we represent such uncertainties?
 - How do we do it tractably?
 - What are the impacts of truncating information?



The University of Texas at Austin Aerospace Engineering and Engineering Mechanics Cockrell School of Engineering

Conjunction Assessment





Conjunction Assessment

- The commonly used metric for collision risk is the probability of collision P_c
- This value is fundamentally flawed, but it is the best that we currently have.
- For example: Using measurements with more noise yields a smaller probability of collision.
 - The larger data noise produces a larger posterior density, which becomes larger after propagation.
 - Hence, the probability that a spacecraft is in a given region of space is reduced.
 - This reduces the probability of collision with another object!
 - This is a fundamental flaw because it should give us less confidence in our knowledge of if there is a collision
- What improvements can be made to assess risk to spacecraft?



The University of Texas at Austin Aerospace Engineering and Engineering Mechanics Cockrell School of Engineering

Conjunction Assessment

- Risk indicators must provide information on ignorance
- Risk indicators must be concrete and clear



Image: Delande et al., 2019



Conjunction Assessment

- We have two kinds of uncertainty:
 - Systematic (lack of knowledge)
 - Random (irreducible)
- How do we accurately reflect systematic uncertainty in the conjunction assessment process?
- How do we provide operators with the data necessary to assess risk?
- Image description:
 - The charts on the previous slide depict results from a new method of risk assessment that takes systematic uncertainty into consideration
 - This produces upper and lower bounds on P_c
 - With this approach, the separation between the bounds increases with reduced measurement quality, thereby reflecting systematic error



Information Fusion

• How do we transform measurements into knowledge?







Information Fusion

- How do we go from measurements to knowledge of a space object?
 - In general, data association is non-trivial
 - Optical images provide limited information on location and brightness
 - Brightness provides some data on angular rates, but is ambiguous
 - Spectroscopy can provide information on materials, but is sensitive to observing conditions
- We need new measurement types and improved algorithms for information extraction that help identify spacecraft!



The University of Texas at Austin Aerospace Engineering and Engineering Mechanics Cockrell School of Engineering

Tracking Dim Objects



- How do we track small (i.e., dim) objects with low signal-to-noise?
- How do we handle the joint detection and tracking problem?

Movie: Courtesy of Shahzad Virani and Marcus Holzinger, Georgia Tech



The University of Texas at Austin Aerospace Engineering and Engineering Mechanics

Influence of New Space on SSA







Influence of New Space

- Many advancements will be driven by the New Space industry
 - Getting into space is increasingly inexpensive
 - Vehicle launches are getting cheaper
 - Kilo-constellations (1,000s of spacecraft)
 - Proliferation of cube-/small-sats
- This yields a discrete jump in the number of trackable space objects
 - How do we adjust to such changes in the near future?
 - What are the operational impacts?
 - What are the recommended practices for new space operators?
 - What level of cooperation is require to be successful?
- What are the impacts to existing practices and methods?
 - Example: Common $P_c = 10^{-4}$ no longer a feasible risk threshold!



Resource Utilization

• How do we use sensor resources for SSA?



- What is the utility of data available?
- Example: Do we need 1M observations of the International Space Station?

Image: Gehly et al., 2018a



Resource Utilization

- Data is becoming increasingly common
 - Multiple universities produce SSA data
 - Multiple companies produce volumes of SSA data
- With so much data, what is its *utility*?
 - How much data is sufficient?
 - How much should data cost?
- What modes of operation are appropriate?
 - Custody maintenance versus precise orbit determination
 - Searching versus tracking of space objects



ASTRIAGraph: Knowledge Graph for Space Domain Awareness ASTRIAGraph





The University of Texas at Austin Aerospace Engineering and Engineering Mechanics



http://sites.utexas.edu/bajones

http://sites.utexas.edu/moriba

http://sites.utexas.edu/russell

